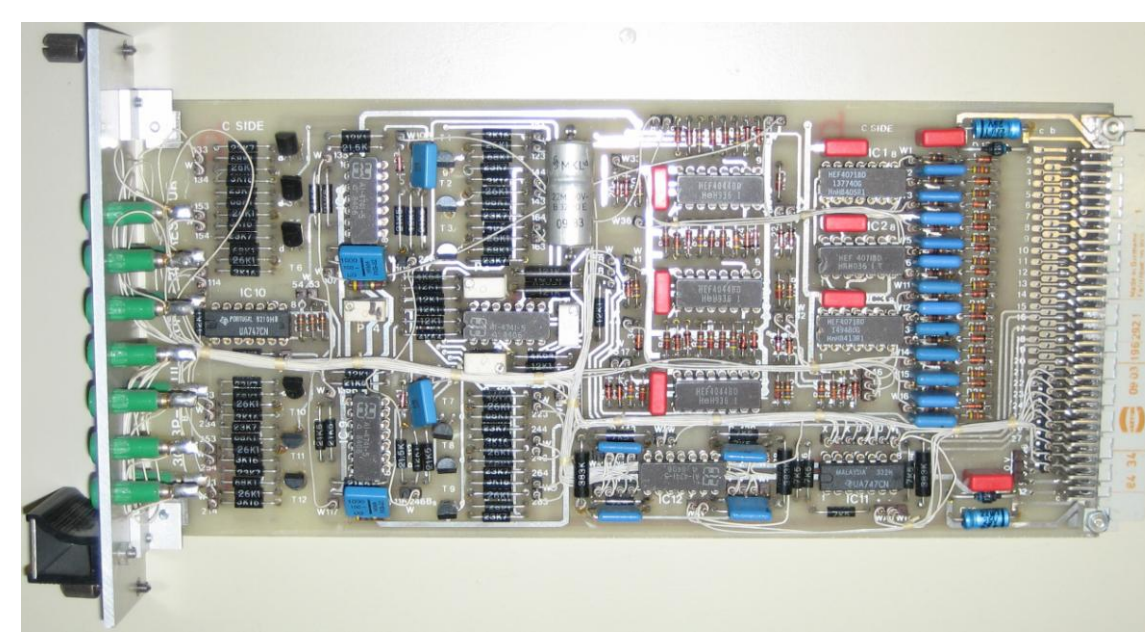
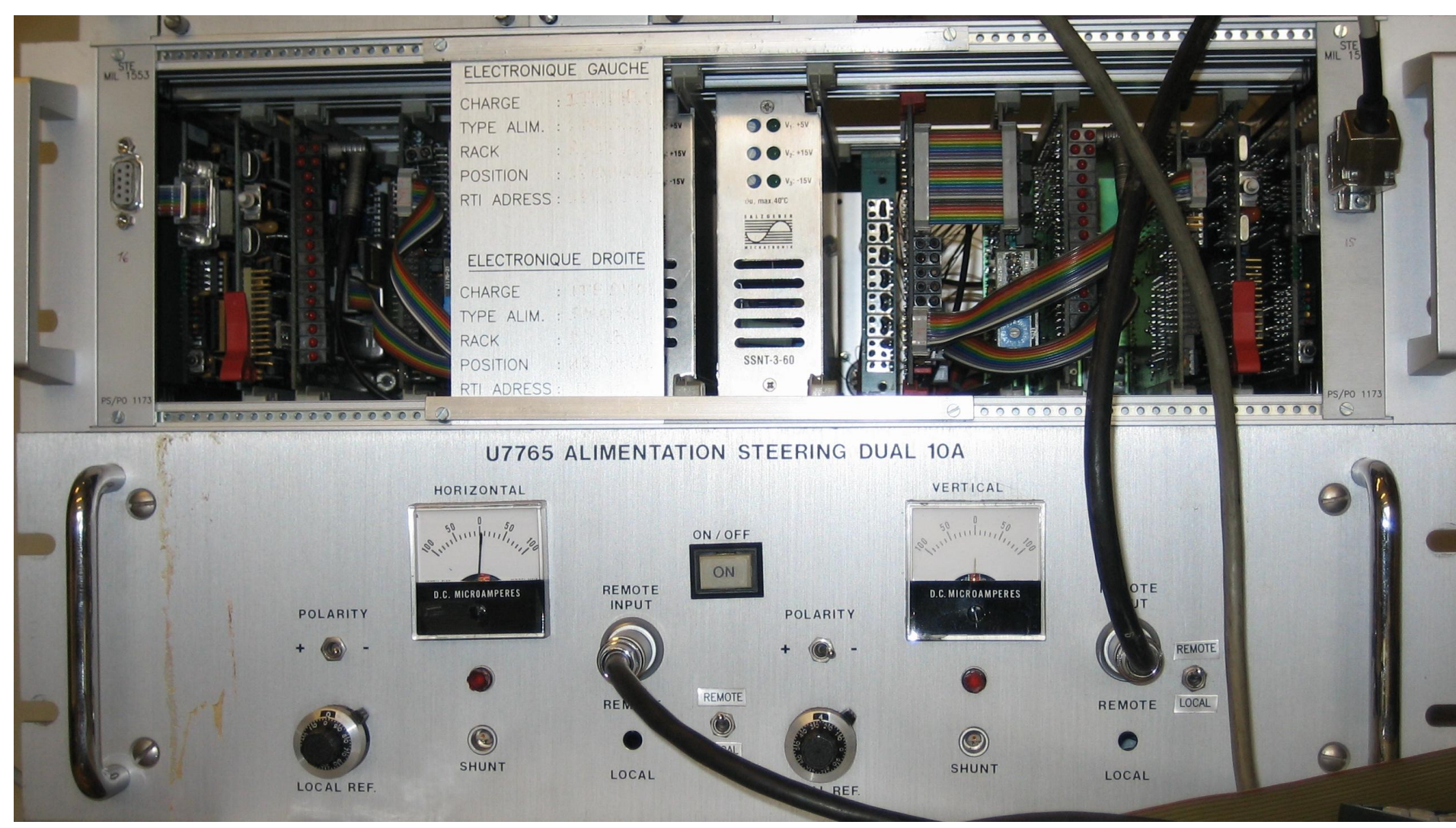
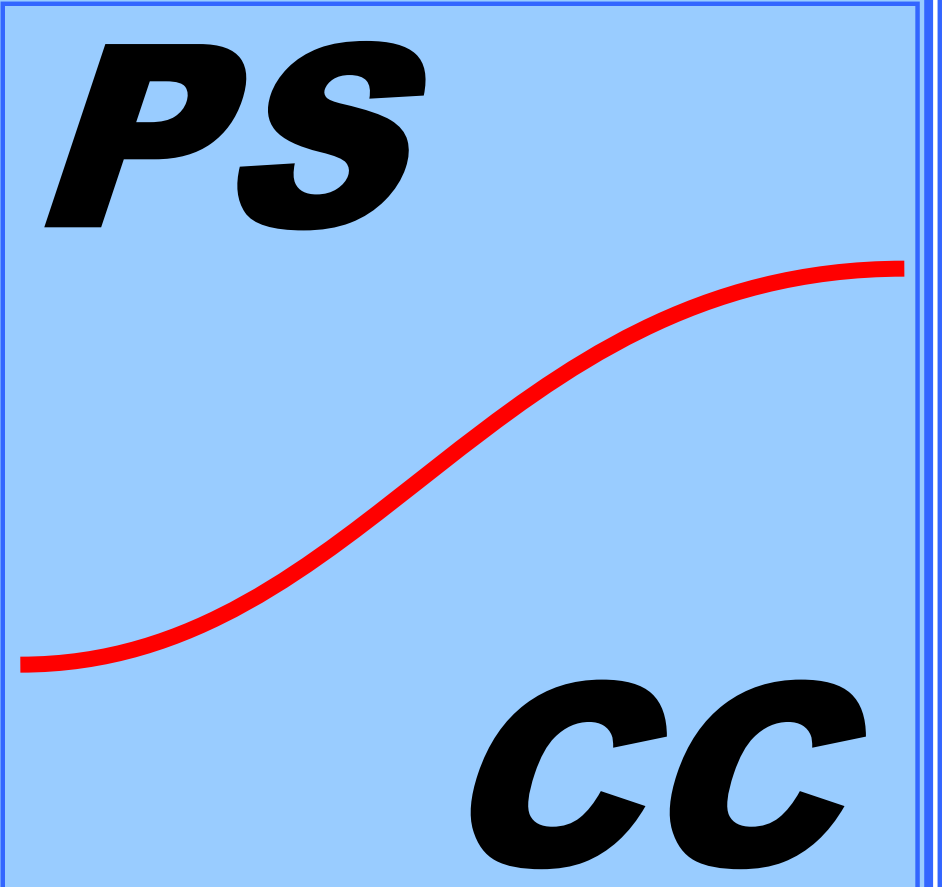




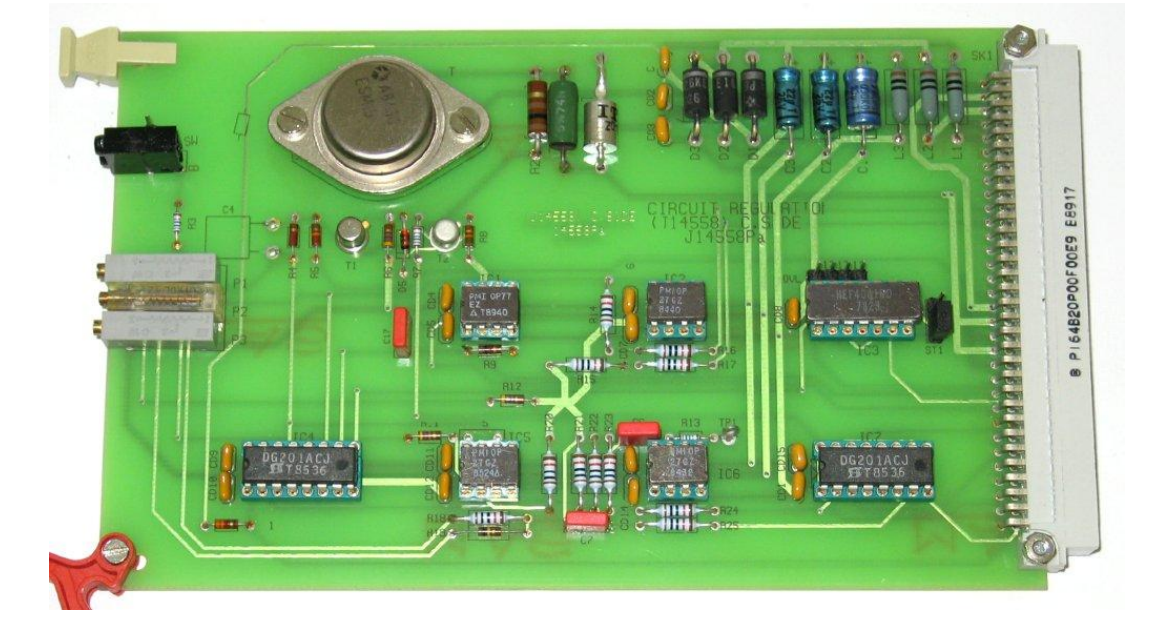
# The G-64 Chassis at CERN after 25 years of operation

D. Calcoen, CERN



Timing and charge

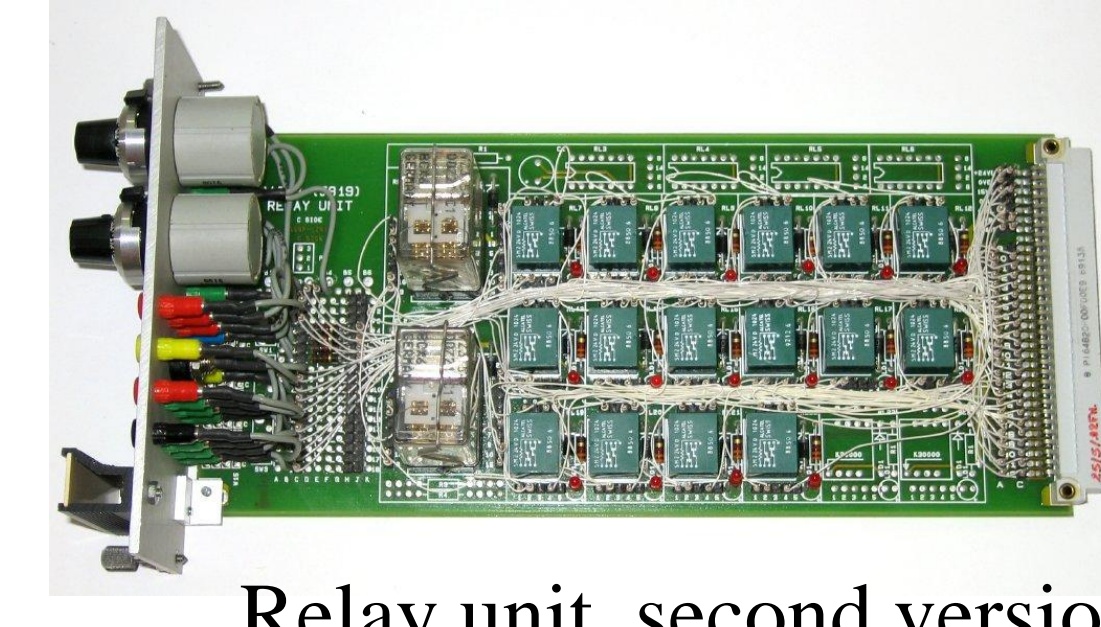
Some of the modules used in G-64 chassis



Regulation circuit



CAMAC - Transceiver

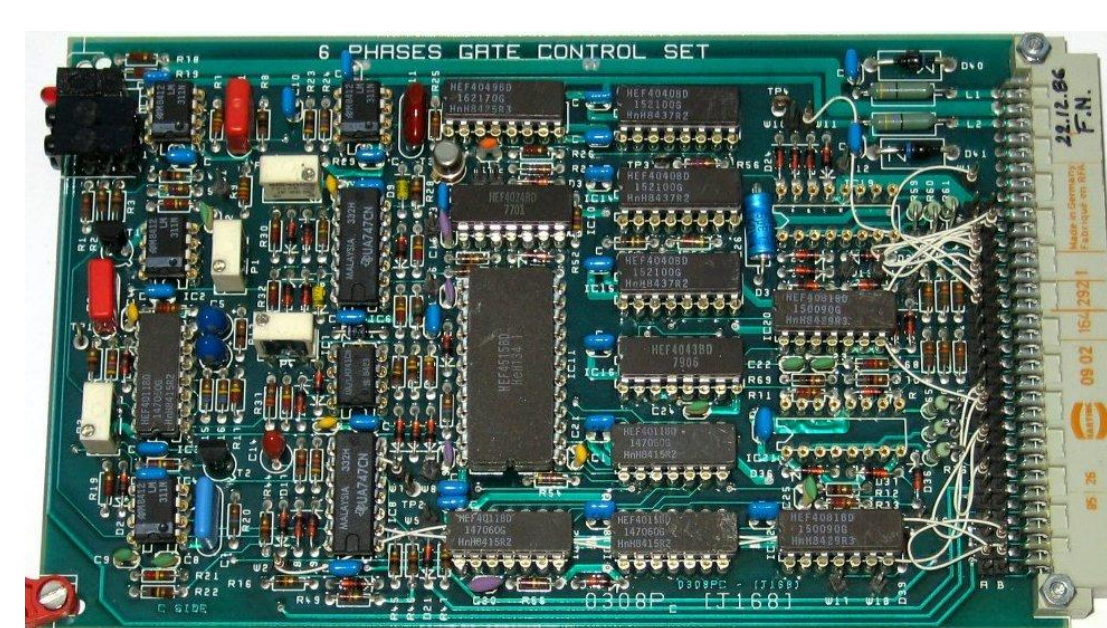


Relay unit, second version

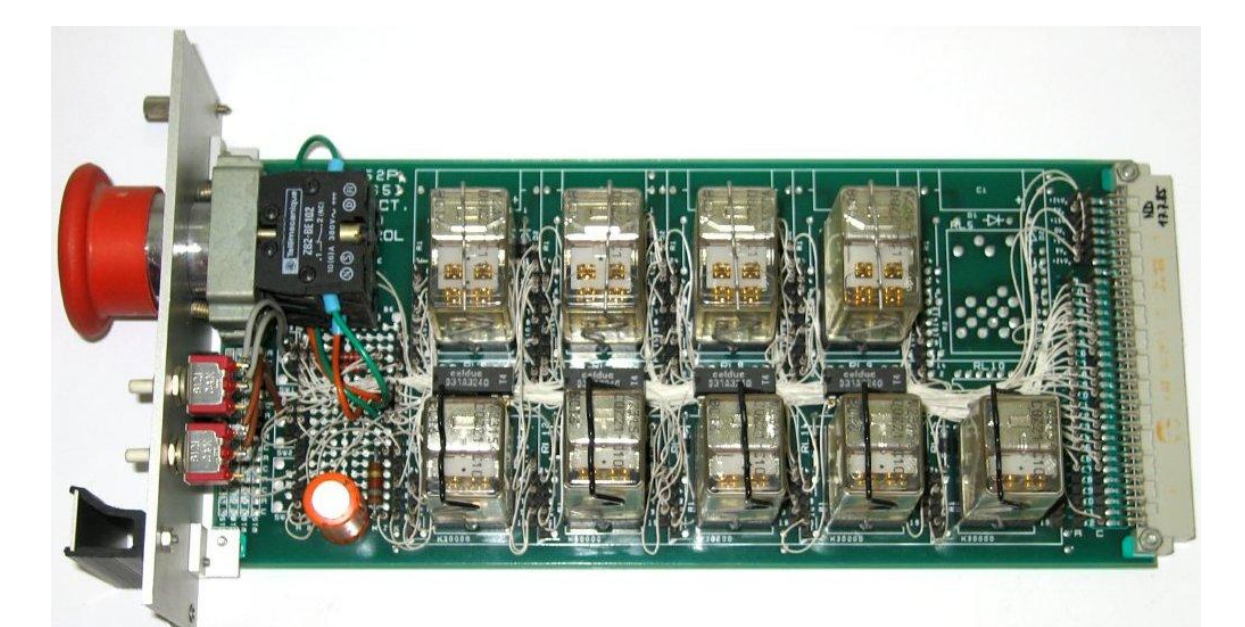
Which decisions taken by the designers in the 1970s allowed this hardware to still operate effectively in 2005, despite the amazing changes we have witnessed in electronics during the past 25 years?

The key elements include:

- ✓ Modular approach
- ✓ Reliable connectors
- ✓ Simple design
- ✓ Easy-to-handle card size
- ✓ Mechanical robustness

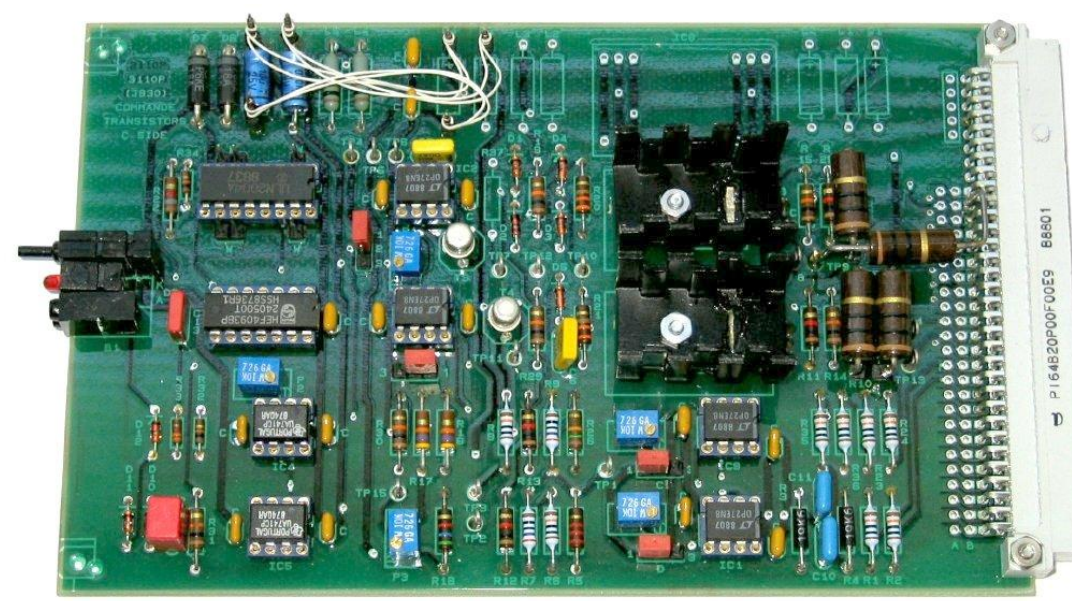


6-phase gate control

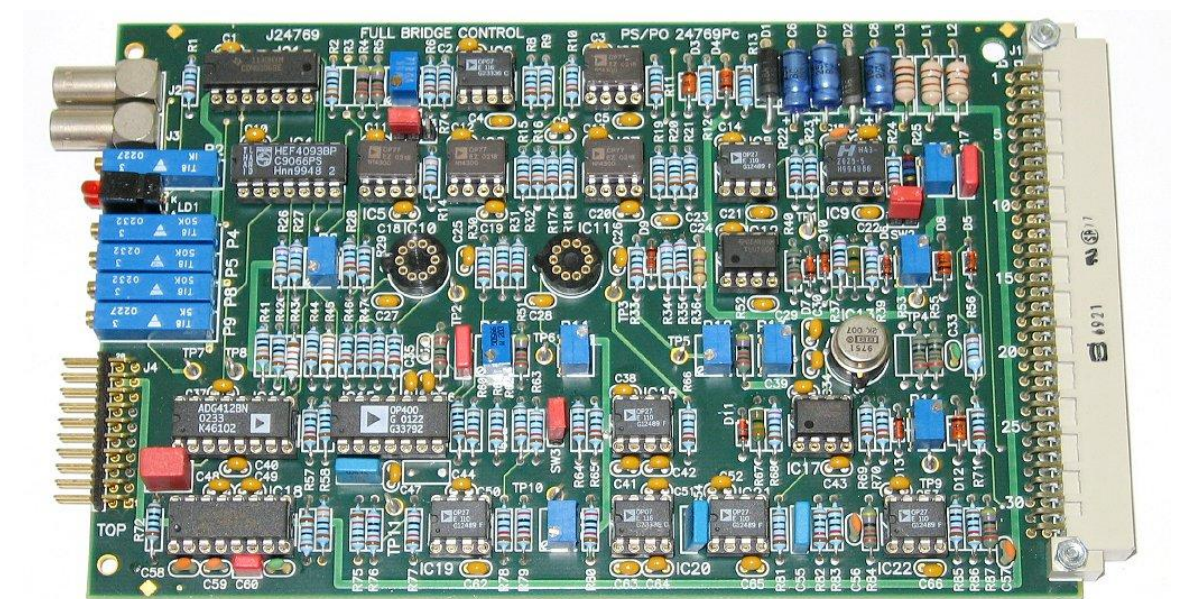


Relay unit 2

The solution had to be extremely flexible to provide the required performance enhancements over the years as well as completely new functionalities. Numerous modules had to evolve as components became obsolete, but overall the systems continued to operate.



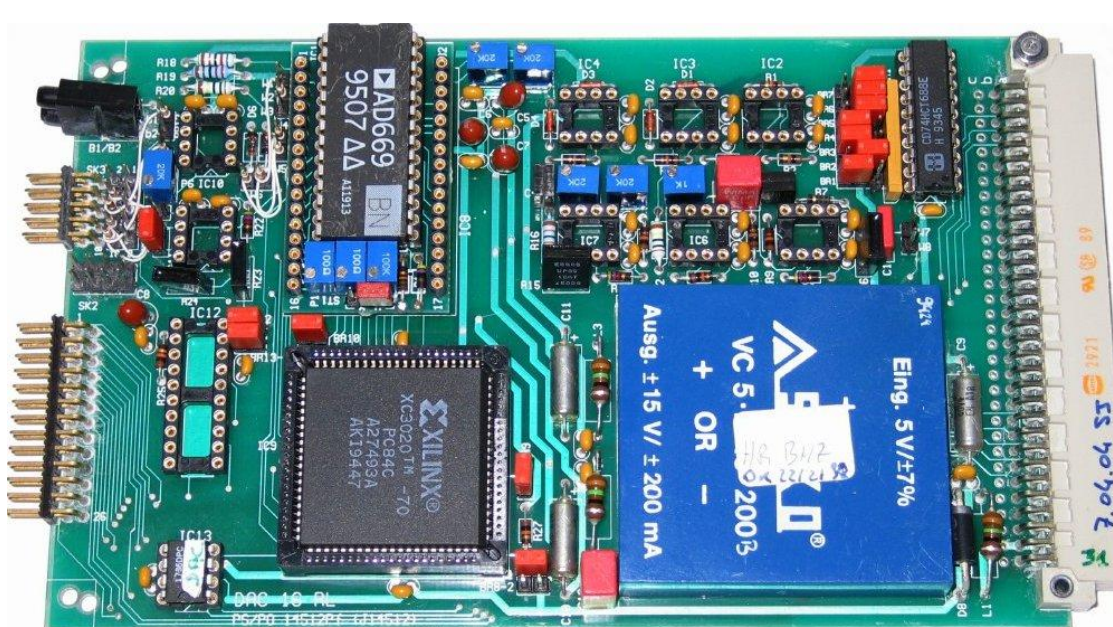
Transistor driver



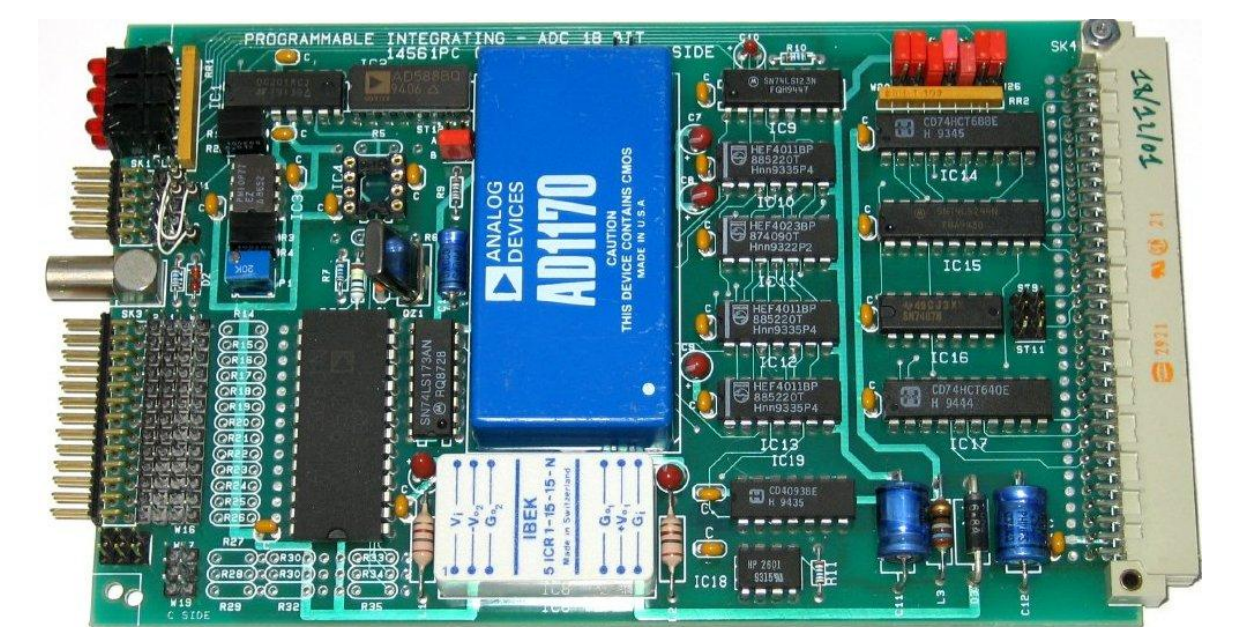
Full bridge control



600W Power Converter with the first version of display and keyboard

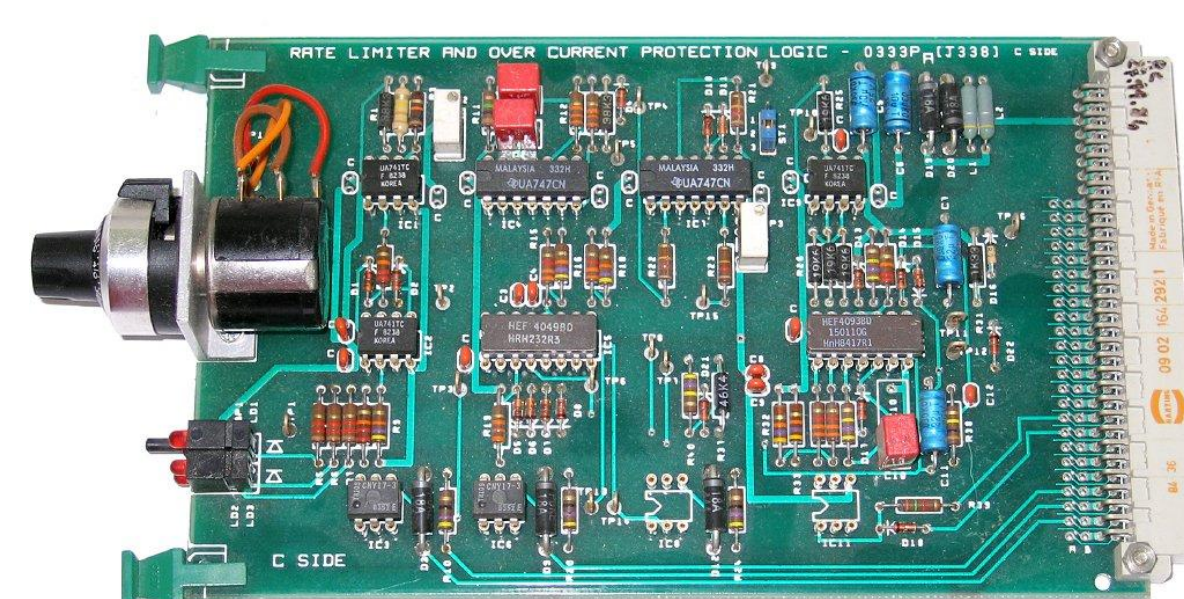


DAC, 12/14 or 16-bit

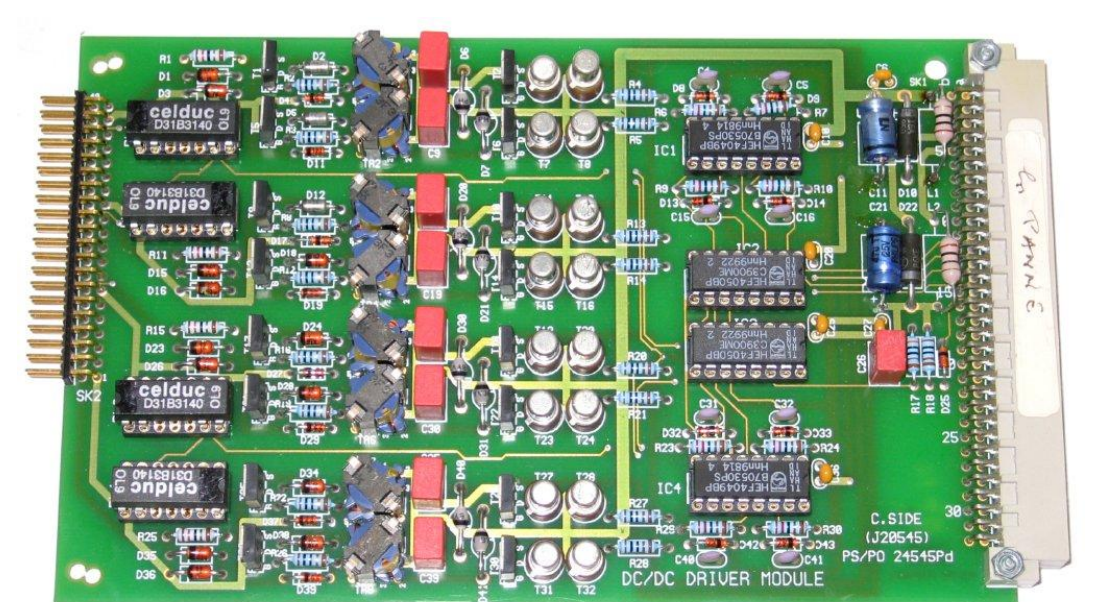


Integrating ADC, 18-bit

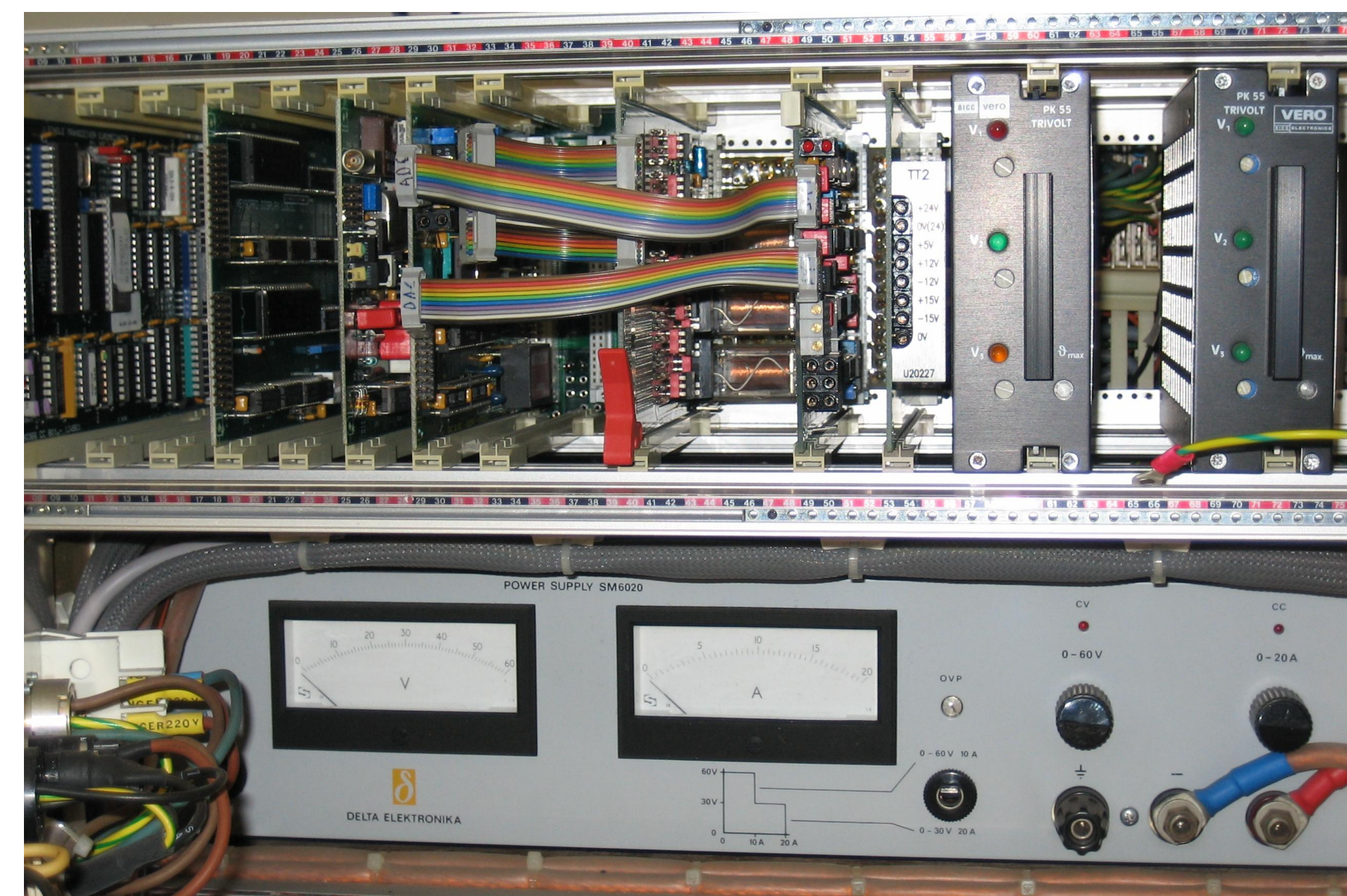
Now as we prepare a new solution to replace the G-64 chassis (hopefully to work for the next 25 years!) we find that in the 21<sup>st</sup> century it is the software that has become the hardest part of the development. A modern 15-Euro DSP has more computing power than a super-computer from 1980, but software development techniques and tools have not kept up.



Rate limiter and over-current protection



DC/DC driver



Pulsed Power Converter with the fourth version of display and keyboard

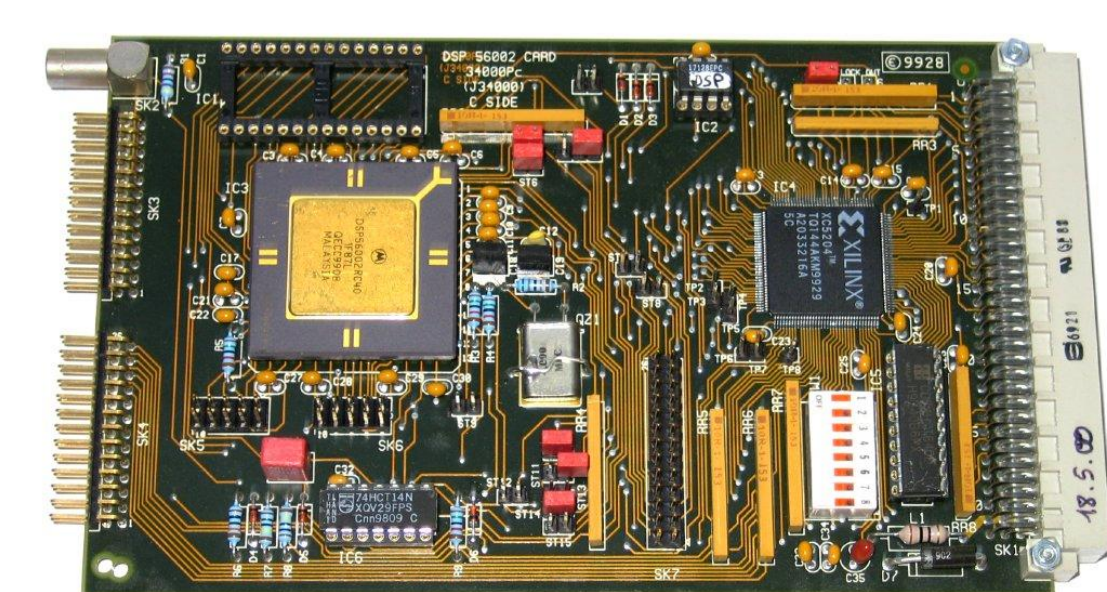


16-bit ADC, second version

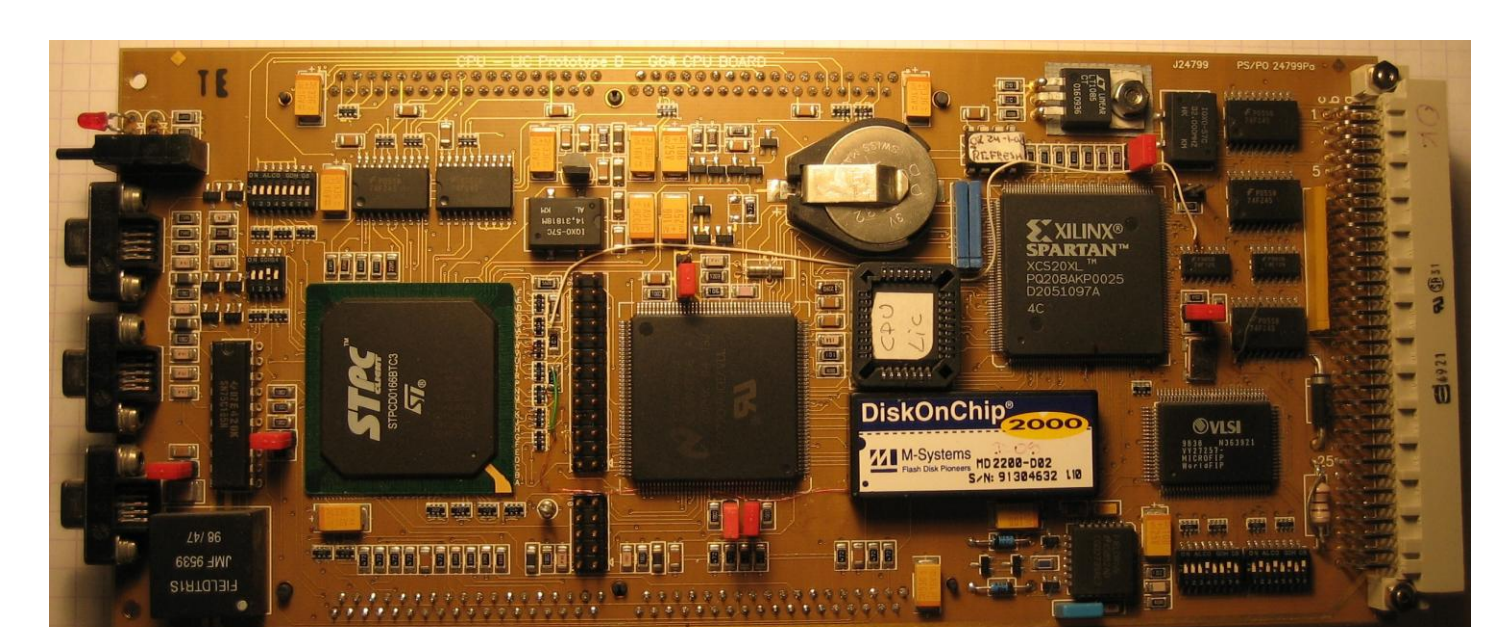


MC6809 CPU, third version

Systems must now be built to run standard software and not the other way around.



Digital Regulation with DSP, third version



PC compatible CPU